

In preparation for head removal, the service structure and refueling canal both were decontaminated, and the lifting and handling equipment was tested. As part of a complete safety evaluation, engineers conducted a head-drop analysis, verifying that the components below could withstand such an impact. Looking for debris that could make head removal difficult, analysts took debris samples from the top of the plenum assembly and found the materials there were nonpyrophoric.

Two final projects in preparing the head for removal are currently underway. Workers are installing the canal seal plate, which will close the gap between the mouth of the reactor vessel and the refueling canal, and they are installing a temporary defueling water cleanup system as a precaution, should an unexpected event require the refueling canal to be flooded for shielding during head lift.

As Figure 1 illustrates, the second major step toward disassembly is moving the plenum assembly to the shallow end of the refueling canal, where it will be stored under water until its removal. The plan is to first jack the plenum up from its current seated position and then lift it from the reactor vessel using the polar crane.

In 1983, major advances were made in designing tools to inspect and remove the plenum. Four 60-ton hydraulic jacks are being custom designed for the job. From a central pumping station, four operators will hand-pump the jacks, lifting the plenum slowly and in small increments so it may be continuously monitored from top to bottom to check for clearance and prevent jamming. Engineers are already aware from video inspections of the plenum's underside that partial fuel assemblies still hang from the plenum. After initial jacking, workers will knock off these stubs using a tool that is now in the design stages.

Once the plenum assembly is lifted, engineers will wrap it in a large, semirigid plastic bag, called the transfer contamination barrier, and place the entire assembly in the shallow end of the refueling canal. Figure 1 indicates that the final major step to the TMI-2 reactor disassembly is removal of fuel and debris from the reactor vessel. GPU Nuclear and TI&EP engineers have been concentrating on a number of aspects of this task, including a major defueling water cleanup system, fuel removal tools, and canisters in which to ship the fuel and debris.

The extensive defueling water cleanup system to be installed essentially consists of two subsystems, one to provide water filtration and processing for the reactor vessel and contamination barrier, and a second to provide water filtration and processing for the refueling canal and spent fuel pool A (see Figure 1).

Clearly, a key element to defueling is the fuel removal tooling, to which engineers and designers have been devoting much of their efforts. Westinghouse Electric Corporation, selected as contractor to design and fabricate these tools, suggested two designs for consideration. The first design-a manual, remote defueling system-reflects the technical specifications previously established for the necessary mechanical equipment and vacuum and separation equipment. The vacuum would remove fine materials as small as 10 µm and debris as large as fuel pellets. The system would then separate the debris from the water and load the debris into canisters.

Westinghouse's second proposed design also meets the technical specifications, but it is a more automated approach to defueling. The system would use robotic arms to position a vacuum hose and load into a shredder materials too large for vacuuming. All of the debris then would be pumped in a slurry out of the reactor vessel for separation and canister loading. After discussing options for fuel canisters, TI&EP and GPU Nuclear representatives selected a design wide enough to hold intact cross sections of fuel assemblies. This canister is, however, shorter than anticipated because engineers do not expect to be shipping any full length fuel assemblies; few if any appear to be intact. A benefit to using this canister design is the potential cost savings; government-owned rail shipping casks may be available for transporting the canisters containing the remains of the Unit 2 core from TMI. \Box

> Demineralizer cubicle A

> > Louie RCTV -

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Robots Reduce Worker Radiation Exposure

Many work areas in the Unit 2 plant contain large amounts of radioactivity and many surfaces are highly contaminated. While workers are protected with anticontamination clothing and monitored with personnel dosimeters, the effort to keep exposure rates low is a challenging one. Researchers are finding that robots can take the place of humans for many tasks in high radiation areas. A look at two robots, destined for use at TMI, illustrates their useful role in reducing human radiation exposures.

"Left-handed Louie" comes to TMI from Westinghouse Hanford Operations after a long history of remote-control work in a variety of environments. Louie's official name is the Remotely Controlled Transporter Vehicle, or RCTV, but since an anonymous technician during the 1950s scrawled "Louie" on the robot's arm, the RCTV has been known by its more humanlike name. Louie will assist in a crucial waste handling operation at TMA, that of monitoring the removal of the Makeup and Purification System demineralizer resins from their tanks.

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During the accident, reactor coolant water flowed through the Makeup and Purification System for nearly 18 hours and deposited significant amounts of contaminants on the resins in the purification system demineralizer tanks. Extensive efforts to determine exactly how contaminated these resins are have shown that cesium activity levels in the resins may far exceed known values for any other accident-generated waste in the plant. Research work reported in both the August and December 1983 issues of the Update obtained dose rate readings of 3000 R/h in the A cubicle, and 1000 R/h in the B cubicle.

The contaminants in the resins are soluble fission products. They will be removed through a series of rinsing and elution steps conducted remotely through specially adapted plant systems. Dose rates inside the purification resin tank cubicles are much too high to permit human workers to enter routinely, but the resin tanks must be repeatedly monitored to see if the rinsing and elution steps are decontaminating the resins. Left-handed Louie will be used for the job. As shown in Figure 2, Louie will carry a gamma radiation detector into a resin tank cubicle and hold the detector in a predetermined place up against the tank wall. Technicians seated at control panels outside the cubicles can then monitor gamma radiation levels.

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Figure 2 Louie will enter the demineralizer cubicle to monitor gamma activity in the resin tank during cesium elution.



Figure 3 Louie's 1.3-m manipulator arm will help monitor cesium levels in a high radiation area.

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Louie's components include a transporter base, a telescoping tube, a manipulator arm, three cameras, lights, and a 30-m-lor.g control cable. Pictured in Figure 3, Louie's telescoping tube and manipulator arm have a combined vertical reach of 2.9 m, which is ample height to reach nearly to the top of the 3-m-high demineralizer tanks. Its manipulator arm can reach as far as 1.3 m horizontally in any direction. Louie's strength will not be needed for its demineralizer work, but the telescoping tube can hoist up to 450 kg, and the manipulator arm can lift and maneuver up to 68 kg.

Louie's cameras are radiation hardened, and will be the operating technician's "eyes" in the cubicles, not only for positioning Louie and the gamma monitor correctly, but also for observing conditions inside the cubicles during the rinsing and elution processes. The 30-m cable connecting the transporter to the control console outside the cubicles weighs nearly 23 kg.

This robot is a simple one, whose every movement must be dictated by the operating technician. It has no ability to interpret commands or repeat activities on its own. Classed as a "inaster-slave"

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robot, it is basically a hot cell manipulator arm on a transporter. But its simplicity does not diminish its usefulness to the cleanup task in which it will serve. The radiation monitor Louie will carry will help determine when the 137Cs concentrations in the demineralizer resins have been reduced to the lowest practical level. Operating technicians will conclude the rinsing and elution process when the gamma detectors show no change in readings after two consecutive elution cycles. Louie could be exposed to dose rates of up to 3000 k/h in the course of the cesium elution process. Its use will greatly reduce the human exposure risks involved in the important task of eluting and removing the purification system resins from the plant.

Robots may play a key role in the defueling of the reactor vessel, scheduled to begin in late 1986. A remotely controlled tool positioning system called ROSA might be used in place of longhandled tools handled by human workers in the Reactor Building. ROSA is a Westinghouse Electric Corporation robot; its name is an acronym for Remotely Operated Service Arm. It can be used in connection with a Westinghouse-designed defueling system to remove all debris from the damaged Unit 2 reactor.

Research has shown that the accident reduced much of the original core to a bed of rubble. The top 1.5 m of the core is now a large cavity, with a volume of approximately 9.5 m^3 . Into this cavity, cleanup engineers will lower a variety of special equipment. Small, loose debris will be vacuumed out of the core into shipping canisters located inside the Reactor Building. Large debris will be reduced to a smaller size and then removed to shipping canisters. Material fused to the rubble bed will be cut loose with cutting shears, chisels, and drills. Items to be removed intact for research studies will be placed into debris baskets hanging inside the core. ROSA can do the lifting, rearranging, and positioning required for these special defueling activities.

Westinghouse's ROSA, shown on a transporter in *Figure 4*, is a manipulator arm with humanlike articulation at a "shoulder," "elbow," and "wrist." Its

flexibility comes from its modular design. The arm consists of six segments, each of which is a self-contained unit with a motor, gear train, brake, and position indicators. Constructed of lightweight alloys, the arm is very strong for its 54-kg weight. When fully extended to its 2-m length, ROSA can lift 23 kg; when the arm is close to its base, it can lift more than 90 kg. With special adjustments, ROSA may be able to lift even more weight. ROSA's arm joints are all electric, but are completely watertight so the arm will work well in the flooded vessel and cana'.

Figure 4 ROSA's "shoulder," "elbow," and "wrist" move to commands issued through a computer.



A 180-m umbilical cable will connect ROSA to its control computer, to be located in a trailer outside the Reactor Building. This computer, containing several microprocessors operating in parallel, is ROSA's train. For manual control, an operator sits at the control console, issuing commands with a joystick. The computer translates these commands into arm movements.

Unlike the movements of such masterslave robots as Louie, ROSA's movements do not need to be dictated step-by-step. The computer calculates the arm joint movements required along six different axes to move the arm in the manner indicated by the joystick. The calculations are performed in a fraction of a second, and the arm responds almost immediately.

ROSA's computer can be preprogrammed with complete instructions for any standard task. The arm can also be taught to perform a specific activity. An operator first leads ROSA through the activity with the joystick and then instructs the robot to repeat that activity, unsupervised. ROSA's memory records all the information necessary to repeat the activity indefinitely. Both the preprogramming and the teachability will be useful for repetitive, tedious tasks.

Westinghouse developed ROSA in the early 1980s and has used ROSA in steam generator repair work and inside reactor vessels. ROSA would remain the property of Westinghouse during its use at TMI. Indeed, it would be accompanied by a Westinghouse technical adviser and operated by Westinghouse technicians. But the robotic arm can far outwork its human counterparts. While they are restricted to eight-hour days, ROSA can work without rest or maintenance for 1500 nonstop hours. ROSA's flexibility, strength, and ease of operation can help to complete the defueling operation safely and efficiently.

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Louie and ROSA can complete vital cleanup tasks along the road to cleanup of the TMI-2 plant. They are designed to be versatile, and each could be used for jobs not discussed here. GPU Nuclear is working with the Electric Power Research Institute and Carnegie-Meilon University to develop another robot for performing characterization and cleanup tasks, and the potential for using robots in other areas in the future continues to be examined. These machines can play a useful role in both simple and complex jobs as they help keep human exposure as low as is reasonably achievable.

Source Term Assessment Continues at TMI

The Tl&EP continues to make progress in its studies of source term, recently completing visual inspections of the TMI-2 Reactor Coolant Drain Tank (RCDT) and investigating the concentration of radioiodine and tellurium in the reactor core and building basement. In a related effort, GPU Nuclear engineers took concrete core samples on the 305-ft and 347-ft elevations to assess radionuclide penetration into the concrete.

The RCDT was the major pathway for the release of accident water into the Reactor Building basement. In video inspections of the tank below the vent line, analysts saw a dark, particulate sediment of less than 0.32 cm thick, nonuniformly distributed on the bottom. Personnel also saw particles larger than they predicted would have been released through the pressuriser to the drain tank; they calculated a maximum particle size of 30 μ m.

During each of these inspections, samples of the water and sediment were extracted for analysis. By studying the samples, personnel at the Idaho National Engineering Laboratory (INEL) will determine the quantity of fuel and fission products released to the RCDT. The resulting data will also support ongoing analyses of fission product mass balance and source term—the concentration and distribution of radionuclide activity.

In defining the source term in Unit 2, program personnel are placing special emphasis on determining the concentration of 129 and 130 Te in liquid and solid samples collected from the reactor core and Reactor Building basement. Data collected to date indicate that the fraction of radioiodine released from the core to the basement is significantly less than the fraction of radiocesium released to the oasement. Basement sediment samples are being analyzed to determine if the radioiodine precipitated. Lead screw and core grab samples are being analyzed for ¹³⁰Tewhose behavior is important because it is a parent of iodine-to determine if plateout or scavenging of the tellurium significantly reduced the amount of radioiodine released from the core.

To assess the extent to which radionuclides migrated into the concrete in the building, engineers obtained 17 samples of concrete from the 305-ft and 347-ft elevations. (The basement concrete was not included in this study because of its inaccessibility.) Tests on these large core samples, obtained using a concrete boring tool, resulted in one significant finding: that the majority of radionuclides released from the Reactor Coolant System (RCS) into the Reactor Building environment were trapped in the concrete's surface coatings.

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Most concrete surfaces in TMI-2 are protected with epoxy-based, nuclear-grade coatings, making an otherwise porous concrete resistant and easier to decontaminate. Pictured in Flgure 5 is a sample of concrete taken from the D ring wall at the 305-ft elevation. To its right is the sample's autoradiograph, which documents the coating's ability to absorb radionuclides and prevent them from penetrating the concrete. Only where the coating was scarred and the unprotected surface was exposed to contaminated water for an extended period of time did analysts discover significant radionuclide penetration.

The analysts then removed the coatings from the samples to see if this would effectively decontaminate the surfaces; and up to 98.5% of total activity measured was removed with the coating.

While analysis are not saying widespread coating removal in TMI-2 is necessary, it may be beneficial in areas where long-term personnel operations are planned. A GPU Nuclear report suggests devising other equally effective decontamination methods as alternatives to coating removal.

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Figure 5 This concrete core sample, whose coating was accidentally chipped during removal, was taken from the D ring wall at the 305-ft elevation. Its autoradiograph, at right, shows dark shading where the coating protected the concrete rom radionuclide penetration.

Hydrogen Burn Study Answers Questions About Its Cause and Damage

After two years of research and analysis, TI&EP engineers completed their studies of the hydrogen burn that occurred at TMI, answering a number of questions generated from the event and gaining a better understanding of its cause and its damage.

Overall, analysts concluded that the hydrogen burn caused little damage to the Reactor Building itself and no damage to safety systems. The damage that was found, for the most part, was fully consistent with TI&EP expectations.

The burn occurred about 10 hours into the accident, after the reactor core overheated and the zircaloy cladding that encased the fuel reacted with steam, liberating large quantities of hydrogen to the building, where the gas later ignited. The estimated pressure rise time for the event was 10 to 15 seconds, but most of the 28-psig pressure increase occurred in the final 3 to 6 seconds.

Evidence, such as charred paint and cables, indicates a flame rose from the building basement to the dome, where it remained until quenched.

The precise location and ignition source of the flame are unknown and may always be so, but evidence indicates the burn originated on the building's west side, in the basement. Among the candidate sources of the burn is the electrical equipment on two Motor Control Centers that wipped at the time of the event. Access to the 282-ft level will provide further insight into the ignition source and location.

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Location of hydrogen release

Calculations by several researchers





TMI Program Highlights Available ori Videotape

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The H&EP has released a videotape program for loan without charge. "1983 in Review: A DOE TMI 2 Programs Bitef." is a 16-minute program highlighting the accomplishments of 1983 a TMI. The program covers the shipment of the last processing container used to decontaminate accident water, experiments to immobilize the containinated contents of this and other containers, the study of the hydrogen burn event, tests to determine cable and connection, performance in accident and postaccident environments, sampling of the tubble bed in the core, and fabrication of a clear plastic model of the cavity in the damaged relator, among other acinevenents.

This videotage may be obtained by contacting Kan Haddock; EGEG Idaho Inc. 1MI Sile Office, P.U. Box Bi, Middletown, PA 17057, telephone FTS 390-1019/or (717) 948-1015.

DOE Studies of Ion Exchange Media Focus on Gas Generation and Resin Degradation

Through DOE research into the accident at TMI, laboratory personnel have learned a great deal about organic and inorganic ion exchange media, both of which have been part of the cleanup process there. Researchers analyzed the media in the EPICOR II prefilters, Makeup and Purification System demineralizers, and Submerged Demineralizer System (SDS) liners, focusing specifically on two major concerns: radiolytic generation of combustible gases and resin degradation. Organic ion exchange resins were used alone or in combination with inorganic scolites in the 50 EPICOR II prefilters that decontaminated accident water from the Auxiliary and Fuel Handling buildings. Research on the EPICOR II ion exchange media focused specifically on radiolytic generation of combustible gases, resin degradation, and liner integrity. Laboratory scale studies have shown that at doses of about 10⁷ rads and more, residual water in the organic resin decomposes and the resin itself degrades. Both processes generate gases which could lead to combustible gas mixtures in containers during handling, shipping, or storage.

The radiolytic decomposition of water produces hydrogen, which accumulates in sealed containers, and oxygen, which is consumed during a reaction with the organic resin and water in the container. The hydrogen gas generation rate is. dependent on the radiation dose to the water and organic resin: the rate increases in a nearly linear relationship with an increasing curie content (see Figure 8). Internal pressure in a sealed container will at first decrease sharply as oxygen in the air inside the container is consumed by a chemical reaction. The dose delivered to the organic resin acts as a estalyst for this reaction. When all the oxygen has reacted, the ongoing radiolytic process builds up hydrogen gas



the container, causing an increase in container pressure above atmospheric pressure. At TMI, potential hazards associated with this bydrogen gas

concentrations in

potential hazards associated with this hydrogen gas buildup in sealed containers led DOE researchers to develop a tool to solve the problem. A gas sampler with a remotely operated support facility safely vented, sampled, and purged gases in waste containers. The remote operation reduced both man-rem exposure and potential hazards associated with hydrogen gas.

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In a closer look at resin degradation, analysts characterized the two worst-case EPICOR II prefilters and found that the pH of the ion exchange media was acidic and became significantly more so from top to bottom of the bed. But resin degradation, such as surface cracking, spalling, and fragmentation due to radiation exposure appeared to be minimal. This minimal degradation was observed at the bottom of the bed, far from the highest activity loading. Thus, it likely was the result of high moisture content or chemical attack. Analyses also demonstrate no significant leaching of nuclides from the resin and essentially no threat to liner integrity. And results of metallurgical studies suggest that the liners can be disposed of safely for more than 300 years in high-integrity containers without any threat to the environment.

Studying the two Makeup and Purification System demineralizers, analysts focused on resin degradation due to irradiation and high temperatures. After five years of radioactive decay, demineralizer A contains approximately 5000 Ci of cesium, and demineralizer B holds about 14,000 Ci of cesium. To date, these resins have absorbed a dose of more than 10⁹ rads. In addition, fission product decay heat likely produced temperatures of up to 811 K. As expected, this combination of high temperatures and radiation dose caused the demineralizer resins to degrade; the bed size reduced by about 70%.

Samples of both demineralizer beds were sent to Oak Ridge National Laboratory for analysis. Demineralizer A was found to be dry, with agglomerated, black resin fragments, indicating temperatures in excess of 672 K and extensive radiation damage. Analysts have not concluded whether this vessel's resins are sluicible, but they have confirmed that demineralizer B resins likely can be sluiced because they remained under water.

As expected in resins irradiated to the high levels found in these two vessels, radiolysis produced hydrogen and oxygen gases. Analysts say the hydrogen generation and oxygen depletion mechanisms observed in these resins were the same as in the EPICOR II system ion exchange media. Before sluicing, the cesium will be removed by elution from the resins and processed by the SDS zeolites, whose abilities to handle such high curie loadings has been proven.

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SDS was the third system at TMI in which an ion exchange medium was used. The inorganic zeolites in these liners effectively processed about 3785 m³ of contaminated water from the reactor coolant bleed tanks, the RCS, and the building basement.

Below a dose of 10⁹ rads, inorganic zeolites do not suffer radiation degradation; the only effect of the extremely high curie loading is radiolytic generation of hydrogen and oxygen gases. Focusing their studies on this concern, analysts have found that gas generation rates are approximately proportional to curie loading. Also, the oxygen depletion mechanism found in organic resins does not occur with inorganic zeolites to the same degree. The measured fraction of hydrogen was greater than stoichiometric, but oxygen was generated in sufficient quantities to form a combustible mixture in a sealed container.

Zeolite liners in storage at TMI exhibited gas generation rates of nearly 1 L/h. Rockwell Hanford Operations developed a catalyst recombiner and vacuum outgassing system to solve the gas generation problem. Vacuum outgassing removed residual water, and palladium catalyst pellets recombined the radiolytic gases generated from both the residual and chemically bound water so the liners could be safely shipped from the Island.



UPDATE



Core Topography System Data and Photos Give First Accurate Picture of Core Void

As reported in the December 15, 1983, issue of the Update, engineers lowered a sonic sensing head into the TMI-2 core and collected nearly 500,000 data points to acoustically map the size and shape of the cavity inside the damaged reactor.

Since then, these individual data points have been reconstructed into the threedimensional clear plastic model pictured in *Figure 9*. This model is the first accurate map of the upper portion of the core, which experienced considerable damage during the accident.

The model shows in some places the void extends all the way to the edge of the core. The suspended materials in the model are axial power shaping rods, which were driven in after the accident, and stubs of fuel assemblies. After studying the results of the core topography system, engineers have determined the cavity volume to be approximately 9.5 m³. At the deepest point, the cavity drops about 2 m, as measured from the underside of the plenum.

Figure 9 Mike Martin, senior project engineer, explains the making of this clear plastic model of the core void, developed from nearly 500,000 data points.

These findings are also supported by videotapes of the region between the pienum and rubble bed. Figure 10 shows the stubs of fuel assemblies hanging unsupported from the underside of the reactor plenum. Data from the sonar mapping device indicate these segments typically are 5 to 25 cm long. A clos. shot, seen in Figure 11, reveals an exposed fuel rod plenum spring. In Figure 12, the core former wall is clearly visible and appears in most places to be undamaged. Just in one area on the east side of the reactor does the core former wall appear to bow outward by about 6 cm.

Figure 10 Stubs of fuel assemblies hang from the underside of the plenum assembly.





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Figure 11 This fuel rod broke off close to the end fitting, exposing the fuel rod plenum spring.

Figure 12 Although the void extends, in most places, to the edge of the core, the core former wall appears undamaged.





Only the top 1.5 m of the nearly 4-mtall core are visible to analysts at this time; the area below is still unknown. But looking down, the video camera has provided some clear photographs of the rubble bed. In Figure 13, fractured fuel rods lay like pickup sticks on the surface of the gravel-like rubble bed. Fuel rod plenum springs are also visible there (see Figure 14). And contrary to earlier conclusions based on limited visual observations, the surface of the rubble bed is uneven. In one region of the rubble bed, engineers saw a "valley," which they speculate was created during the accident by upward water flowing through the rubble bed.

Figure 13 Fractured fuel rods lie scattered across the surface of the rubble bed.

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Figure 14 in a closer shot, fuel rod plenum springs are also visible on the rubble bed surface.





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Figure 15 Sections A-A and B-B are topographical plot cross sections of the TMI-2 core void.

Using the data collected from the serie sensing head, engineers also were able to plot cross sections of the void. Two such cross sections are presented in *Figure 15*. The solid lines in these drawings were produced from actual data, while the dashed lines are approximate locations obtained by extrapolation or interpolation. (A few areas of the rubble bed were not within the range of the acoustic transducers.)

Section A-A of *Figure 15* shows the deepest point of the void, at Position P, where water possibly flowed, as explained earlier. The bottom of this narrow channel is about 2 m into the core. In Section B-B, the data points plotted in the center of the cross section jut up into the void. As videotapes of this region confirm, this protrusion is a partial fuel rod and its associated hardware, which fell from the plenum into the rubble bed.

As a result of this information, analysts have concluded that 135 of the total 177 fuel assemblies in Unit 2 are broken, thus creating the void in the top 1.5 m of the core. Of the remaining 42 assemblies, 19 are more than 50% intact (including the two possible fully intact assemblies), and 23 are less than 50% intact. Again, these numbers strictly pertain to the known 1.5 m of the core. This and other sonar topographic data are still being evaluated and will be useful in planning for plenum and fuel removal.

Engineers plan this year to answer some questions about the unknown region below the currently defined void by analyzing more samples taken from deep in the rubble bed.

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First Samples of Core Debris Analyzed

These six samples shown at right were the first obtained from the damaged TMI-2 reactor core. After their removal last fall, five of the samples were sent to the INEL and the sixth to Babcock & Wilcox laboratories in Lynchburg, Virginia, where they were weighed and photographed.

At the INEL, analysts removed eight particles from the five samples for gamma spectroscopy and fissile determination. The core debris consisted of fuel pellet fragments, shards of cladding or guide tubes, and particles which appear to be glazed with previously hiquid material. Five of the eight particles were primarily fuel. While ^{144}Ce , ^{106}Ru , and ^{154}Eu appeared to be associated mostly with the fuel, ^{137}Cs and ^{125}Sb were released from the fuel particles. Based on a limited analysis, the released cesium and antimony appear to be present on other core materials. Radiation levels for the five samples, using a teletector from 2.5 cm away, ranged from 3 to 36 R/h gamma. Particle sizes ranged from about 0.6 cm to a fine debris. One surface sample consisted of 13 large chunks of material.

Future work will address the chemistry of the debris in all six samples. The information from the debris samples will aid in assessing the tools and procedures required to defuel the TMI-2 reactor. In addition, the data will be used to define the behavior of a commercial reactor core under the accident conditions found in TMI-2.

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MONITORS MAY Investigations of failed radiation monitors st TMI-2 NOT BE have revealed that the causes of failure are not unique SUITABLE FOR to an accident environment. Failures experienced by monitors at TMI could occur in similar nonqualified BUILDING USE monitors in operating plants, indicating that these monitors may not be suitable for reactor building use.

Incorrect installation instructions supplied by vendors and installation problems are among the factors. associated with radiation monitor failure at TML Investigations of one monitor revealed that the cable connector attaching the cable to the monitor was not. screwed on properly. This improper seal allowed water to enter the connector and accumulate on the connector pins, causing a short circuit. The situation was aggravated by the fact that the entire monitor was installed upside down. Ambiguous instructions in the manufacturer's installation manual led technicians to install the monitor with the cable connection facing the ceiling. The manufacturer has since corrected the manual.

The manufacturer advises against subjecting monitors to pressures greater than 30 psig. During standard reactor building integrated leak rate tests, sealed equipment can experience differential pressures as high as 69 psig. Consequently, TMI-2 monitors had to be removed from the building during each integrated leak rate test. This only increased wear-and-tear on the instruments and the potential for installation mistakes.

Investigations have also shown that radiation monitors with connecting cables longer than 152 m can fail at radiation levels as low as 500 mR/h. The failure mode, called a foldover effect, causes control room ratemeters to show decreasing radiation levels, when in fact the levels in the plant may be increasing. The foldover is caused by a normally inconsequential impedance mismatch along the cable connecting the monitor to the ratemeter. As radiation levels increase, the instrument circuit operates at a higher frequency and the mismatch is amplified, causing a faulty drop in the ratemeter readout.

The foldover effect is amplified by another factor associated with failure of radiation monitors. Monitor components called metal oxide silicon transistors are known to degrade with accumulated radiation exposure. The TMI studies reveal that their degradation also compounds the foldover effect.

All TMI-2 studies indicate that these monitors may be suitable for use in a reactor building. While the monitors perform satisfactorily in support building environments, they are subject to failure in the harsh environments which can be encountered in reactor buildings. 🗍 🐇



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